



Wen, Y., Chen, Y., Zhang, Y., Chen, H., & Yu, S. (2016). Winding light beams along elliptical helical trajectories. *Physical Review A*, 94(1), [013829]. <https://doi.org/10.1103/PhysRevA.94.013829>

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## Winding light beams along elliptical helical trajectories

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(Received 25 March 2016; published 15 July 2016)

Conventional caustic methods in real or Fourier space produced accelerating optical beams only with convex trajectories. We developed a superposition caustic method capable of winding light beams along nonconvex trajectories. We ascertain this method by constructing a one-dimensional (1D) accelerating beam moving along a sinusoidal trajectory, and subsequently extending to two-dimensional (2D) accelerating beams along arbitrarily elliptical helical trajectories. We experimentally implemented the method with a compact and robust integrated optics approach by fabricating micro-optical structures on quartz glass plates to perform the spatial phase and amplitude modulation to the incident light, generating beam trajectories highly consistent with prediction. The theoretical and implementation methods can in principle be extended to the construction of accelerating beams with a wide variety of nonconvex trajectories, thereby opening up a route of manipulating light beams for fundamental research and practical applications.

DOI: [10.1103/PhysRevA.94.013829](https://doi.org/10.1103/PhysRevA.94.013829)

The seemingly counterintuitive discovery that light fields with appropriate initial field distributions such as Airy distribution [1,2] capable of winding light beams as propagating along curved trajectories—known as accelerating beams—in free space has led to extensive research interests, as such optical phenomena may enable potential applications including optical micromanipulation [3], laser plasma filamentation [4], “light bullets” [2,5,6], imaging [7], and plasmonics [8–12]. Nevertheless, Airy beams only move along parabolic trajectories, which limit the flexibility in practical applications, so a number of researches have been carried out to extend the variety of beam trajectories. Direct phase engineering in real space under the paraxial approximation successfully constructed nonbroadening beams moving along arbitrary convex trajectories at the cost of giving up propagation invariance [13]. Going beyond the paraxial condition in real space enabled large-angle bending of the trajectory [14]. These works can be categorized as the caustic method in real space. In addition to phase engineering in real space, similar works have also been carried out in Fourier space [15–17]. However, only convex trajectories are realized based on these caustic methods because the first derivative of the trajectory is required to be single valued. Limited types of nonconvex trajectories are obtained by other approaches, such as by superposing some specific beams (e.g., circular beams) to construct periodic accelerating beams over an overall convex trajectory [16,18–20] or by imposing a spiral-shape phase or amplitude modulation to incident beams [21–24].

On the other hand, most of the experimental realization of winding light beams has been based on phase-only spatial light modulators (SLM). In order to achieve high quality beams with low side-lobes, both amplitude and phase modulation would be required. Some schemes have been proposed to implement both phase and amplitude modulations in the generation of accelerating beams. One scheme is to encode both phase

and amplitude modulation into a phase-only SLM [20], which is more suitable for a binary amplitude modulation, otherwise it will introduce unwanted phase change and noise from other diffraction orders. Another scheme is to position a printed amplitude mask [16] or a linear filter [25] close to the phase-only SLM to realize additional amplitude modulation, but accurate alignment between the amplitude and phase modulation elements is a major problem in such a configuration. Techniques of generating structured light beams have experienced a general evolution from bulk optical elements toward compact and robust integrated optical devices, exemplified in the case of vortex beam in Refs. [26,27]. Applying such integrated approaches to the generation of accelerating beams should also enable the engineering of the optical phase, amplitude, and even polarization in a more accurate, compact, and robust fashion [28].

In this work we demonstrate the winding of light beams along arbitrarily elliptical helical trajectories in free space [Fig. 1(a)] by developing a superposition caustic method and by means of an integrated optics approach.

A helical beam’s 2D accelerating trajectory can be separated into two orthogonal 1D sinusoidal trajectories under the paraxial approximation. It is noted that the meaning of 1D and 2D here refers to the transverse profile of a light field and should not be confused with surface plasmonic waves propagating in a 2D plane [8–12]. Hence a 1D-accelerating beam with a sinusoidal trajectory is to be constructed first. Our method is based on the caustic method in Fourier space, where an accelerating beam moving along a curved trajectory is constructed by the interference of plane waves. Figures 1(b) and 1(c) present this interference process in a simplified light-ray picture with each red ray tangent to the predesigned trajectory representing the plane wave in need [29]. The relation between a predesigned trajectory and its necessary plane waves in a previous caustic method [16] can be summarized as (see the Supplemental Material for a detailed derivation [29])

$$\frac{k_x}{k} = f'(z), \quad \theta''(k_x) = \frac{z}{k}, \quad r(k_x) = [\theta'''(k_x)/2]^{1/3}, \quad (1)$$

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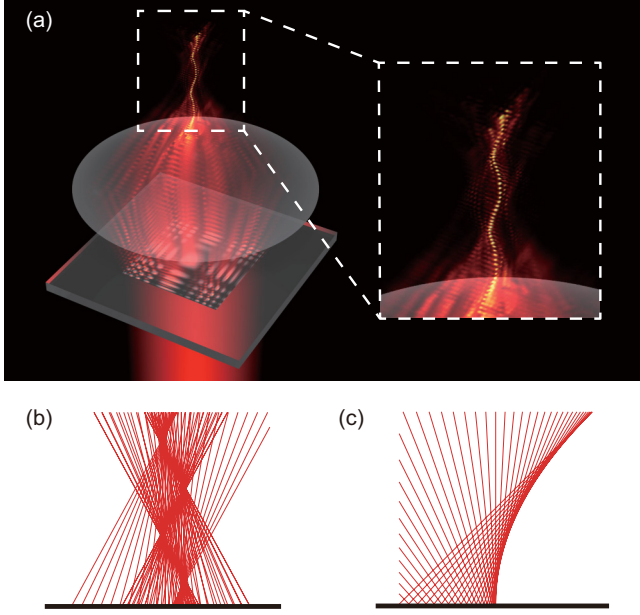


FIG. 1. Schematic view and construction principle of an elliptical helical beam. (a) An illustration of the realization of a helical beam. (b) The transverse acceleration dynamics of 1D sinusoidal beam described as a bundle of rays compared with (c) the well-known Airy beam accelerating along a parabolic trajectory. The rays represent key spatial frequencies of light emanating from the initial plane (the thick black line at the bottom), and their interference forms a local intensity maximum along a curve.

where  $k_x$  and  $k$  are the spatial frequency and wave number in free space,  $r(k_x)$  and  $\theta(k_x)$  are the amplitude and phase of the initial spatial spectrum  $A(k_x)$ , and  $f(z)$  is the predesigned trajectory. Only if  $f'(z)$  is single valued can we obtain the necessary initial spatial spectrum, which limits the trajectory to be convex as mentioned before [Fig. 1(c)].

To construct nonconvex beams, we break this limitation by dividing the entire trajectory into several segments so that each segment is convex and thus corresponds to an initial spatial spectrum according to Eq. (1). If, over the space of one particular segment, the intensity along the main lobe of this segment is much higher than the side lobes in the same space resulting from the other segments, the interference between these segments along the main lobe is negligible, and the entire nonconvex trajectory can be obtained by simple linear superposition of all the initial spatial spectra corresponding to all segments, which can be expressed as

$$A(k_x) = \sum_{j=1}^n A_j(k_x) = \sum_{j=1}^n r_j(k_x) e^{i\theta_j(k_x)}, \quad (2)$$

where the index  $j$  indicates the ordinal of the segments along the propagation ( $z$ ) direction. In this manner, several positions on the trajectory are mapped onto the same spatial frequency, which is different from the one-to-one correspondence for convex trajectories constructed previously [13,16].

Using this superposition caustic method, we are able to connect the beam trajectory with a specific initial phase and amplitude distribution. To perform the necessary phase and amplitude modulation to the incident light beam in experiment,

integrated optics approach is exploited to fabricate a compact and robust optical element. The integrated optics element is fabricated on a quartz glass plate with a size of  $20 \text{ mm} \times 20 \text{ mm} \times 0.5 \text{ mm}$  and the effective area with patterns is  $9.606 \text{ mm} \times 9.606 \text{ mm}$ . This is divided into  $601 \times 601$  pixels with each pixel to be  $16 \mu\text{m} \times 16 \mu\text{m}$ , representing sufficiently high sampling rates in the Fourier space. The phase modulation is implemented by aligned 16-level etching into the fused quartz plate. In each step, the structure is defined using photolithography in a positive photoresist (Shipley S1805), followed by a reactive ion etching process to transfer the pattern into the quartz plate, with each etch depth to be around  $87 \text{ nm}$  deep. The process is repeated 15 times, overlaid using prefabricated alignment marks, so that the phase shift caused by each pixel is defined by the number of times it is etched. The amplitude modulation is realized by controlling the duty ratio

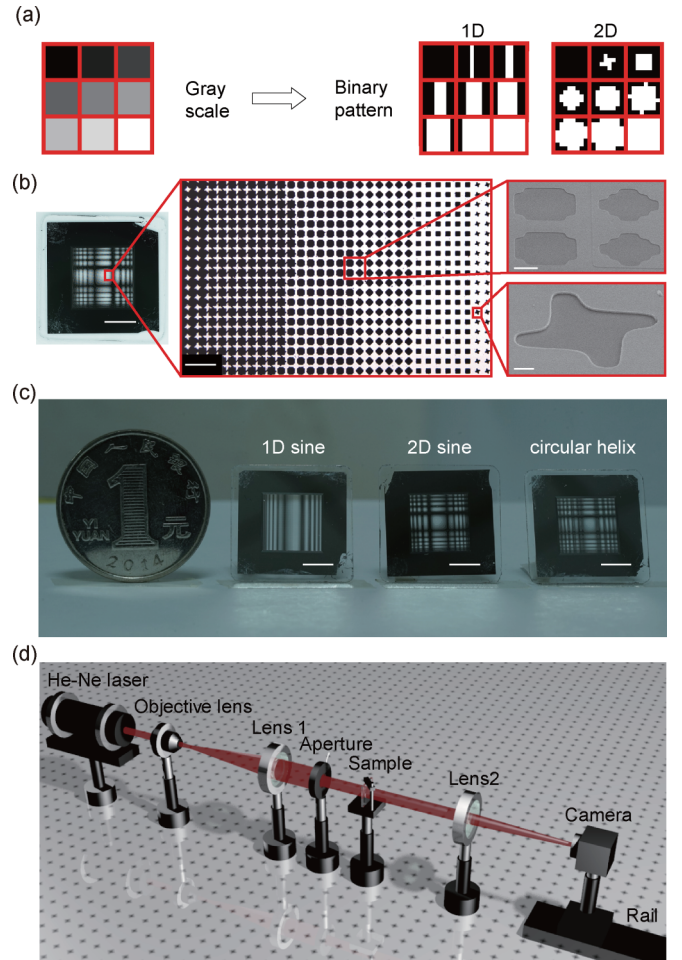


FIG. 2. Experimental implementation. (a) 1D and 2D binary patterns employed to realize grayscale amplitude modulation. (b) Enlarged view of the fabricated sample under the optical microscope and scanning electron microscope (SEM). The scale bar from left to right and from top to bottom is  $5 \text{ mm}$ ,  $50 \mu\text{m}$ ,  $5 \mu\text{m}$ , and  $1 \mu\text{m}$ , respectively. (c) Three fabricated samples for generating the 1D, 2D sinusoidal beams and circular helical beam, respectively, with a scale bar of  $5 \text{ mm}$ . (d) Experimental setup used to generate the accelerating beams as well as measuring their propagation dynamics in free space.

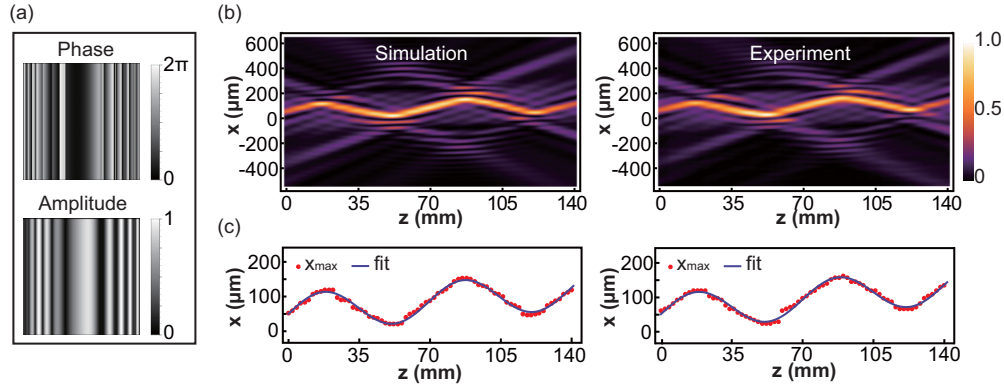


FIG. 3. Generation of the basic 1D sinusoidal beam. (a) The designed phase and amplitude modulation. (b) Simulated and experimental intensity distribution for the beam propagating in free space. (c) Quantitative analysis of the main lobe trajectory. Here red dots mark the positions of the intensity maxima at the cross sections and the blue curves are the fitted trajectories. The fitted curve in simulation is  $x = 50.6 + 0.49z + 54.2 \sin(2\pi z/69.3)$ , while in experiment is  $x = 51.5 + 0.61z + 53.4 \sin(2\pi z/70)$ . The spatial unit is micron for  $x$  and millimeter for  $z$ .

of the partial metal coverage over the pixel. More specifically, each pixel is subdivided into an  $8 \times 8$  grid with each grid to be  $2 \mu\text{m} \times 2 \mu\text{m}$ , and the number of grids with metal coverage is controlled to realize specific transmittance for the whole pixel. Here nine different patterns are used to achieve a nine-level quasigrayscale [Fig. 2(a)]. These patterns are designed with the appropriate symmetry in mind in order to minimize additional diffraction effects. The structure is patterned in the S1805 resist using photolithography. After development, an 80-nm chromium layer was coated using electron beam evaporation and then followed by the standard lift-off process [Fig. 2(b)]. The thickness of the whole micro-optical structures is less than  $1.5 \mu\text{m}$  for the wavelength of 632.8 nm, with the alignment of the phase and amplitude modulation patterns to submicron precision, resulting in a highly compact and robust device for accelerating beam generation. Three fabricated elements for winding light beams are shown in Fig. 2(c).

After completion of the fabrication, an experimental setup, as shown in Fig. 2(d), is used to generate the predesigned accelerating beams as well as investigating their propagation dynamics in free space. A He-Ne laser operating at 632.8 nm emits a linearly polarized Gaussian beam that is expanded and collimated by an objective lens and lens 1. An aperture is used to obtain a quasispherical wave before illuminating the fabricated quartz plate. After transmitting through the plate, the beam passes through lens 2 with a focal length  $f = 500$  mm, placed at a distance  $f$  behind the quartz plate to perform the optical Fourier transform. The predesigned accelerating beam is formed around a distance  $f$  behind lens 2, where a CMOS camera is placed to record the propagation dynamics of this beam by moving along the linear translating rail.

For the 1D sinusoidal beam, the designed initial phase and amplitude modulations varying along only one direction are shown in Fig. 3(a). The beam propagation resulting from this modulation is numerically simulated with a beam propagation method (OptiBPM) [Fig. 3(b)]. A plot of the transverse position of intensity maxima along the  $z$  direction shows that the trajectory fits very well with the sinusoidal curve, apart from a linear term representing a tilt of the beam axis [Fig. 3(c)]. The experimentally measured beam pattern and

trajectory are plotted [Figs. 3(b) and 3(c)] and the trajectory coincides very well with the simulated trajectory, only the linear tilt is slightly different resulting from a slight tilt of the incident beam in the experiment. Moreover, the intensity variance along the main lobe shown in the Supplementary Material [29] (Fig. S3) also has good agreement.

Due to the variables of  $x$  and  $y$  being separable under the paraxial condition, it is straightforward to construct 2D accelerating beams simply by multiplying two 1D field distributions along  $x$  and  $y$  directions [2,17]. Therefore, 2D accelerating beams here with arbitrarily elliptical helical trajectories can be constructed based on two 1D sinusoidal trajectories in  $x$ - $z$  and  $y$ - $z$  planes, respectively. If the two 1D sinusoids are in phase, the helical beam degenerates into a 2D sinusoidal beam, whose projection on the  $x$ - $y$  plane is a line along the  $45^\circ$  angle. The experimental result is shown in Fig. 4(a) and its projections to the  $x$ - $z$  and  $y$ - $z$  planes are similar to the 1D sine beam. Although its projection onto the transverse plane along the  $47^\circ$  angle broadens slightly to an ellipsoid indicating a small phase difference of  $\sim 0.09\pi$  which may result from a slight tilt of the spherical lenses in the experimental setup leading to unequal focal lengths, the experimental results are still highly consistent with the simulation (Fig. S4 [29]).

Furthermore, if a phase shift  $\delta$  is introduced between the trajectories in the  $x$ - $z$  and  $y$ - $z$  planes, winding light beams along arbitrarily elliptical helical trajectories can be realized with the eccentricity  $\sqrt{2|\cos \delta|/(1 + |\cos \delta|)}$  ranging from 0 to 1. For demonstration, we choose  $\delta$  to be  $\pi/2$  and thus the eccentricity becomes zero, corresponding to a circular helical beam. The necessary phase and amplitude modulation as well as the experimental result are shown in Fig. 4. In this case, except for one obvious point deviating from the fitted curve resulting from the imperfect fabrication of the quartz glass plate (detailed analysis in Fig. S5 [29]), the trajectory also coincides well with the simulation results (Fig. S6 [29]).

In conclusion, by way of a superposition caustic method, we break the one-to-one correspondence between the real space position on the beam trajectory and the spatial frequency in the Fourier space caustic method, which enables the



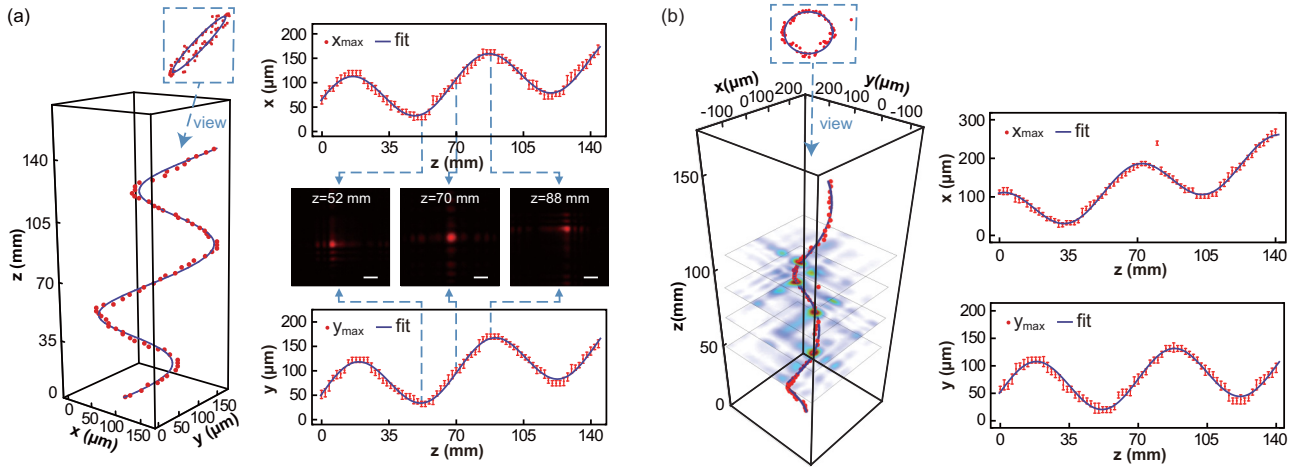


FIG. 4. Realization of a 2D sine beam and a helical beam based on the 1D sine beam. (a) The 3D plot of the trajectory for the main lobe of the 2D sine beam, and its projection to  $x$ - $z$  and  $y$ - $z$  planes (with an error bar showing possible deviation in determining the position of the intensity maximum limited by our CMOS camera), as well as three selected cross sectional intensity distributions, with a scale bar of  $100\ \mu\text{m}$ . Here the fitted curves in  $x$ - $z$  and  $y$ - $z$  planes are  $x = 51.5 + 0.65z + 51.5 \sin(2\pi z/71 + 0.09\pi)$  and  $y = 51.5 + 0.69z + 54.3 \sin(2\pi z/71)$  ( $x$  and  $y$  in microns, and  $z$  in millimeters), respectively. (b) The 3D illustration of the trajectory for the main lobe of the helical beam with four cross sectional intensity distributions presented and its projection to  $x$ - $z$  and  $y$ - $z$  planes. In this case, the fitted curves in  $x$ - $z$  and  $y$ - $z$  planes become  $x = 51.5 + 1.08z + 57.6 \sin(2\pi z/70 + \pi/2)$  and  $y = 51.5 + 0.35z + 49.6 \sin(2\pi z/70)$  ( $x$  and  $y$  in microns, and  $z$  in millimeters), respectively, with an introduced  $\pi/2$  phase shift as designed.

construction of accelerating beams whose main lobe moves along nonconvex sinusoidal trajectories. We experimentally realize 1D sinusoidal accelerating beams using this method. We further construct 2D accelerating beams with arbitrarily elliptical helical trajectories by superimposing two 1D sinusoidal trajectories in the  $x$ - $z$  and  $y$ - $z$  planes and controlling their phase shift. In principle, such a method could be applied to the construction of accelerating beams along a wide variety of other nonconvex trajectories.

We employ an integrated optics approach to the experimental implementation of winding light beams by fabricating micro-optical structures on quartz glass plates to simultaneously provide the designed phase and amplitude modulation with high precision. The method is compact and robust, as confirmed by the high consistency between the experiment and the simulation results, and paves the way for the reliable generation of various accelerating beams by means of photonic integration for practical applications in the future.

This work is supported by the National Basic Research Program of China (973 Program) (2014CB340000 and 2012CB315702), the Natural Science Foundations of China (61323001, 61490715, 51403244, and 11304401), the Natural Science Foundation of Guangdong Province (2014A030313104), and the Fundamental Research Funds for the Central Universities of China (Sun Yat-sen University: 13lpgy65, 15lpgy04, 15lgzs095, 15lgjc25, and 16lgjc16). Y.C. would also like to thank the Specialized Research Fund for the Doctoral Program of Higher Education of China (20130171120012). Y.W. thanks the Undergraduate Training Programs for Innovation and Entrepreneurship (201302071) and SPE's Undergraduate Scientific Research Program (2013011). The authors thank Lin Liu, Chunchuan Yang, and Zengkai Shao for technical assistance in microfabrication, as well as Pengfei Xu, Jiangbo Zhu, Yi Wang, Guoxuan Zhu, and Johannes Herrnsdorf (University of Strathclyde, UK) for helpful discussions.

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